Statistical Inference in the Presence of Ranking Error in Ranked-set Sampling

Omer Ozturk

The Ohio State University

Department of Mathematics June 22, 2011

Omer Ozturk (OSU)

Ranking Error

Izmir Economy Univ and TUBITAK

- Ranked Set Sampling
- Motivation
- 3 Ranking Model
- Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model.
- Applications
- Example
- 8 Conclusion

- Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
- Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model.
- Applications
- Example
- 8 Conclusion

- Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
- 4 Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
- Applications
- 7 Example
- 8 Conclusion

- 1 Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
 - Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
- 6 Applications
- 🕖 Example
- 8 Conclusion

- 1 Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
- 4 Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
- 6 Applications
- 7 Example
- 8 Conclusion

- 1 Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
- Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
- 6 Applications
- 7 Example
- 8 Conclusion

- 1 Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
 - Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
- 6 Applications
- 7 Example

8 Conclusion

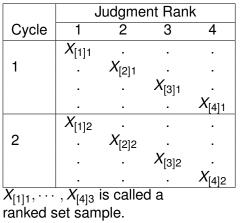
- 1 Ranked Set Sampling
- 2 Motivation
- 3 Ranking Model
 - Performance of Estimator
- 5 Nonparametric Estimate of Judgment Ranking Model
 - 6 Applications
- 7 Example
- B Conclusion

- Select k units at random from a specified population.
- Rank these k units with some expert judgment without measuring them.
- Retain the smallest judged unit and return the others.
- Select the second k units and retain the second smallest unit judged.
- Continue to the process until k ordered units are measured.

Note: These k ordered observations $X_{[1]i}, ..., X_{[k]i}$ are called a <u>cycle</u>. Note: Process repeated $i = 1, \dots, n$ cycle to get nk observations. These *nk* observations are called a <u>standard ranked set sample</u>.

Diagram

Let k=4 and n=3



- For each fully measured unit, we need k – 1 additional units for ranking.
- Measured units are all independent.
- Under a stable ranking condition, observations from the same judgment class are identically distributed.

Motivating Examples: One-Sample Problem

- Let X_{[i]j}, j = 1, · · · , n_i, i = 1, · · · , k be a ranked set sample from distribution F with unique median θ.
- We wish to test $H_0: \theta = 0$ against $H_A: \theta \neq 0$.
- A natural nonparametric test statistic for this test is the sing statistic, S⁺ = ∑_{i=1}^k ∑_{j=1}^{n_i} I(X_{[i]j} > 0).
- Exact null distributing of S^+ involves the convolution of binomial random variables with success probabilities $F_{[i]}(0)$.
- Under perfect ranking F_[i](0), i = 1, ..., k are equal to incomplete beta function and the exact null distribution of S⁺ can be computed.
- Under imperfect ranking, the size of the test is inflated and the coverage probability of the median confidence interval is deflated.

Estimated type I error rates of the signs test and coverage probabilities of the median confidence interval

k	n	ho = 0.5	ho = 0.75	ho = 1.00				
2	5	0.080(0.915)	0.070(0.929)	0.051(0.952)				
	7	0.079(0.921)	0.075(0.926)	0.050 (0.954)				
3	5	0.112(0.888)	0.091(0.909)	0.047(0.952)				
	7	0.102(0.876)	0.084(0.919)	0.053(0.952)				

Motivating Examples: Two-sample problem

- Suppose that we wish to test the location shift between F(y) and $G(y) = F(y \Delta)$. $H_0 : \Delta = \theta_x \theta_y = 0$ against $H_A : \Delta \neq 0$.
- Assume that we have two data sets, one based on a SRS and the other based on a RSS.
- Let \overline{T}_{SRS} and \overline{T}_{BW} be the rank-sum statistics based on SRS and RSS data.
- The statistic \overline{T}_{SRS} is distribution-free under null hypothesis and its null variance is $1/(12\lambda(1-\lambda))$.
- The limiting null distribution of \bar{T}_{BW} is normal with mean zero and variance

$$\sigma_{BW}^{2} = \xi_{1,0}/\lambda + \xi_{0,1}/(1-\lambda)$$

$$\xi_{0,1} = 1/3 - \frac{1}{k} \sum_{i=1}^{k} \left\{ \int F_{[i]}(y) dF(y) \right\}^{2}$$

$$\xi_{1,0} = 1/3 - \frac{1}{q} \sum_{i=1}^{q} \left\{ \int F_{[i]}(y) dF(y) \right\}^{2}.$$

In the property of the second se

Two-sample problem– Continued

- Under perfect ranking, $\xi_{0,1} = 1/3 (2k+1)/(6(k+1))$ and $\xi_{1,0} = 1/3 (2q+1)/(6(q+1))$.
- Under perfect ranking, N = M k = q, T_{RSS} is more efficient than T_{SRS}

$$eff(T_{SRS},T_{RSS})=rac{6(k+1)}{12}.$$

The efficiency is 1,1.5,2.0,2.5,3.0,3.5 when k = 1, 2, 3, 4, 5, 6.

- Under imperfect ranking size of the test is inflated.
- Coverage probabilities of the confidence interval of the shift parameter are deflated.

Izmir Economy Univ and TUBITAK

Motivation

Type I error rates and coverage probabilities

k	n	ho = 0.5	ho = 0.75	$\rho = 1.00$
2	4	0.116(0.894)	0.091(0.917)	0.066(0.947)
	6	0.106(0.887)	0.078(0.915)	0.052(0.944)
	8	0.111(0.903)	0.084(0.920)	0.061(0.942)
	10	0.111(0.894)	0.079(0.917)	0.053(0.950)
	12	0.103(0.900)	0.081(0.922)	0.051(0.946)
3	4	0.139(0.858)	0.115(0.891)	0.065(0.949)
	6	0.139(0.847)	0.107(0.882)	0.054(0.947)
	8	0.151(0.856)	0.115(0.896)	0.050(0.951)
	10	0.145(0.860)	0.115(0.890)	0.051(0.951)
	12	0.142(0.852)	0.107(0.898)	0.053(0.947)
5	4	0.229(0.780)	0.163(0.829)	0.052(0.944)
	6	0.221(0.776)	0.167(0.833)	0.059(0.947)
	8	0.211(0.781)	0.172(0.838)	0.053(0.949)
	10	0.216(0.776)	0.161(0.840)	0.050(0.944)
	12	0.225(0.787)	0.159(0.848)	0.056(0.952)

Omer Ozturk (OSU)

Question:

What should we do when we have ranking error?

- Use balanced ranked set sampling if possible.
- Use robust procedures against imperfect ranking.
- Use a ranking model to explain ranking mechanism.
- Estimate this ranking model and use it to calibrate the tests and confidence intervals.

Bohn-Wolfe Model (Bohn and Wolfe,1994 and Frey, 2006)

Bohn-Wolfe Model (Bohn and Wolfe, 1994 and Frey, 2006)

$$F_{[i]}(y) = \sum_{s=1}^{k} p_{s,i} F_{(s)}(y), i = 1, \cdots, k,$$

where $0 \le p_{s,i} \le 1$ is the probability that the *s*-th smallest unit is assigned a judgment rank *i*.

- The matrix $(p)_{s,i}$ defines a stochastic matrix.
- The quality of judgment ranking is controlled by *p*_{s,i}.
- Identity matrix defines a perfect ranking.
- The entries $p_{s,i} = 1/k, s, i = 1, \cdots, k$ define a random ranking.
- Estimate $p_{s,i}$ and use it to draw inference.

Dell-Clutter Model (Dell and Clutter, 1972, David and Levine, 1972)

Dell-Clutter Model (Dell and Clutter, 1972, David and Levine, 1972)

- The true value of a unit, X_i, in a set is modeled through its perceived value U_i = X_i + ε_i, where ε_i are iid draws from a suitably chosen distribution.
- The sets of (X_i, U_i) , $i = 1, \dots, k$, are ranked with respect to the second component $(X_{[i]}, U_{(i)})$ and the first components are taken as judgment ranked order statistics.
- The quality of ranking is controlled by the noise variable ϵ .
- Monotone Likelihood Ratio model (Fligner and MacEachern, 2006):

Ranking is performed based on monotone likelihood ratio principal.

Estimation of Bohn-Wolfe Model

- Let X_{[i]j}, i = 1, · · · , k; j = 1, · · · , n be a ranked set sample from a distribution F and F̂_[i](y) be the empirical cdf of F_[i].
- Let $z_{(1)} < ... < z_{(N)}$ be the ordered values of $X_{[i]j}$. Define $u_{[i]j} = \hat{F}_{[i]}(z_j), j = 1, \cdots, N$.
- The distance between the Bohn-Wolfe model and the data can be measured

$$D(\mathbf{P}) = \sum_{j=1}^{N} \sum_{i=1}^{k} (u_{[i]j} - \sum_{s=1}^{k} p_{s,i} B_{s,k+1-s}(u_{[i]j}))^2,$$
(1)

where $B_{a,b}(u)$ is the incomplete beta function.

• The number of unknown parameters in **P** is M = (k - 1)k/2. Let **P**^{*} denote these unknown parameters.

Izmir Economy Univ and TUBITAK

 With appropriate notation, the distance function 1 can be written as

$$D(\boldsymbol{P}^*) = ||\boldsymbol{Y} - \boldsymbol{C}\boldsymbol{P}^*||^2,$$

where **Y** and **C** are known kN dimensional vector and $kM \times M$ dimensional matrix, respectively.

• Estimator: We use the minimizer of *D*(*P*^{*}) to estimate the Bohn-Wolfe model

$$\hat{\boldsymbol{P}}^* = (\boldsymbol{C}^\top \boldsymbol{C})^{-1} \boldsymbol{C}^\top \boldsymbol{Y}.$$

- This estimatorv, with direct minimization, may not produce a stochastic matrix. Hence, the estimated ranking model may not be a valid probability model.
- We use constraint quadratic minimization.

Constraint Quadratic Minimization

- We minimize $D(\mathbf{P}^*)$ with repect to \mathbf{P}^* subject to constraint:
 - Constraint 1: $p_{i,j} \ge 0$ for $i, j = 1, \cdots, k$.
 - Constraint 2: $p_{i,j} \leq 1$ for $i, j = 1, \cdots, k$.
 - Constraint 3: sum in each row (and also column) must be equal to one, ∑_{j=1}^k p_{i,j} = 1 and ∑_{i=1}^k p_{i,j} = 1.
- For this minimization, we can use *solve.QP function in R-library quadprog.*

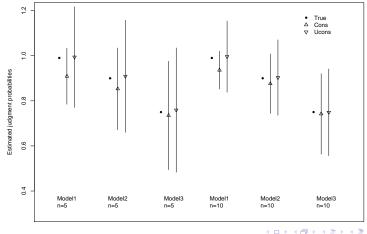
Performance of the Estimator

Consider three different models:

• For *k* = 2

$$\boldsymbol{P}_{1} = \begin{pmatrix} 0.99 & 0.01 \\ 0.01 & 0.99 \end{pmatrix}, \quad \boldsymbol{P}_{2} = \begin{pmatrix} 0.90 & 0.1 \\ 0.1 & 0.90 \end{pmatrix},$$
$$\boldsymbol{P}_{3} = \begin{pmatrix} 0.75 & 0.25 \\ 0.25 & 0.75 \end{pmatrix}.$$
For $k = 2$
$$\boldsymbol{P}_{1} = \begin{pmatrix} .99 & .005 & .005 \\ .005 & .99 & .005 \\ .005 & .005 & .99 \end{pmatrix}, \boldsymbol{P}_{2} = \begin{pmatrix} .90 & .07 & .03 \\ .07 & .86 & .07 \\ .03 & .07 & .90 \end{pmatrix},$$
$$\boldsymbol{P}_{3} = \begin{pmatrix} 0.75 & 0.15 & 0.10 \\ 0.15 & 0.70 & 0.15 \\ 0.10 & 0.15 & 0.75 \end{pmatrix}.$$

The estimate of judgment ranking probability $p_{1,1}$, k = 2



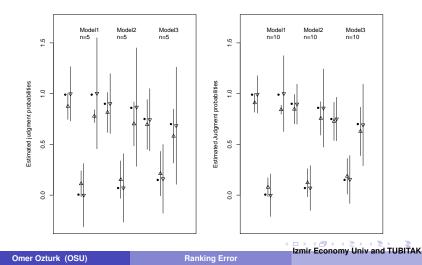
Omer Ozturk (OSU)

Ranking Error

Izmir Economy Univ and TUBITAK

17 / 34

The estimate of judgment ranking probabilities, $p_{1,1}, p_{1,2}, p_{2,2}, k = 3$



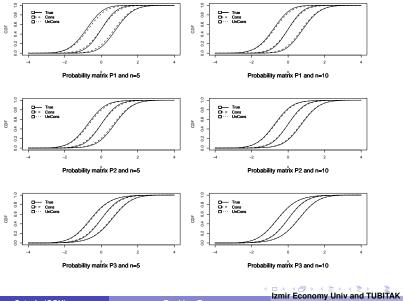
18 / 34

Estimation of judgment class CDF $F_{[i]}$

- Assume that the cdf of the underlying distribution *F* is known.
- From Bohn-wolfe model Judgment class CDF can be estiamted by

$$\hat{F}_{[i]}(y) = \sum_{j=1}^{k} \hat{\rho}_{i,j} F_{(i)}(y), \quad i = 1, \cdots, k.$$

• $\hat{p}_{i,j}$ are the estimates from Bohn-wolfe model.



Omer Ozturk (OSU)

Ranking Error

20 / 34

Nonparametric Estimate of $F_{[i]}$ (Ozturk, 2007)

- Let F_[i](y), i = 1, · · · , k, be judgment class distributions in a ranked-set sample.
- Any sensible ranking model induces a stochastic ordering between judgment class distributions

$$F_{[1]}(y) \stackrel{st}{\leq} F_{[2]}(y) \stackrel{st}{\leq} \cdots \stackrel{st}{\leq} F_{[k]}(y).$$

Let X_{[i]j}, i = 1 · · · , k, j = 1, · · · , n_i, be a ranked set sample from a distribution F and and let F̂_[i](y) be the empirical cdf of F_[i](y),

$$\hat{F}_{[i]}(y) = \frac{1}{n_i} \sum_{j=1}^{n_i} I(X_{[i]j} \leq y),$$

where I() is the indicator function.

- Empirical cdf estimator of F_[i](y) does not satisfy this stochastic order restriction.
- Question: How do we estimate $F_{[i]}(y)$, $i = 1, \dots, k$?

Stochastic Ordering Estimator

- Let $z_{(1)} \leq z_{(2)} \leq \cdots \leq z_{(N)}$ be the ordered values of $X_{[i]j}, j = 1, \cdots, n_i; i = 1, \cdots, k, \phi_{[i]j} = F_{[i]}(z_{(j)})$ and $\phi = (\phi_{[1]1}, \cdots, \phi_{[k]N}).$
- To find an estimator we want to minimize

$$D(\phi) = \sum_{i=1}^{k} \frac{1}{n_i} \sum_{j=1}^{n_i} \{\phi_{[i]j} - \hat{F}_{[i]}(z_{(j)})\}^2$$

subject to constraints

$$\phi_{[i]1} \le \phi_{[i]2} \le \dots \le \phi_{[i]N} \tag{2}$$

$$\phi_{[1]j} \ge \phi_{[2]j} \ge \dots \ge \phi_{[k]j}. \tag{3}$$

• Let *C* be the set of real numbers that satisfy the inequalities (2) and (3). Then our estimator is defined as

$$D(\hat{\phi}) = \min_{\phi \in C} D(\phi).$$
(4)

• There exist a minimizing set $\hat{\phi} \in C$.

Estimator–Continued

The estimator can be written in a closed form

$$F^*_{[i]}(z_{(j)}) = \hat{\phi}_{[i]j} = \min_{1 \le r \le i} \max_{i \le s \le k} B_{rs}(j),$$

where
$$B_{rs}(j) = rac{\sum_{u=r}^s n_u \hat{F}_{[u]}(z_{(j)})}{\sum_{u=r}^s n_u}.$$

 Under some regularity conditions, F^{*}_[i](t) uniformly converges almost surely to F_[i](t), i = 1, · · · , k.

Performance of the Estimator

- The proposed estimator satisfies the stochastic order restriction.
- Both empirical cdf and the new estimators are uniformly consistent for $F_{[i]}(t)$. Thus, we expect that both estimators satisfy the stochastic order restriction for large sample sizes.
- For small sample sizes, empirical cdf estimator may violate the stochastic order restriction. In this case, the proposed estimator combines the data across judgment classes where the violation occurs, so we expect it to perform better.
- For small sample sizes, the new estimator has smaller IMSE (Integrated mean square error).
- The proposed estimator has smaller MSE than the empirical cdf estimators.

Efficiency of the estimators, $R_1 = I(E)/I(N)$, $R_2 = I(E)/I(BW)$, $R_3 = I(N)/I(BW)$.

			ho = 1			ho = .075			
k	n	i	R_1	R_2	R_3	R_1	R_2	R ₃	
2	5	1	1.038	8.960	8.368	1.099	6.173	5.616	
	7	1	1.023	9.329	9.115	1.079	5.975	5.539	
	10	1	1.011	9.238	9.134	1.058	5.444	5.146	
3	5	1	1.057	7.025	6.645	1.169	4.479	3.833	
		2	1.128	5.398	4.784	1.337	4.263	3.187	
	7	1	1.035	6.872	6.642	1.126	4.346	3.859	
		2	1.084	5.289	4.879	1.270	3.853	3.033	
	10	1	1.023	6.391	6.244	1.095	3.873	2.827	
		2	1.051	5.149	4.897	1.198	3.386	2.827	
5	5	1	1.070	4.897	4.578	1.229	2.356	1.917	
		2	1.209	2.719	2.249	1.563	2.349	1.502	
		3	1.257	2.493	1.983	1.700	2.438	1.434	
	10	1	1.034	4.429	4.282	1.143	2.242	1.961	
		2	1.103	2.320	2.104	1.401	2.087	1.489	
		3	1.133	2.119	1.870	1.490	2.539	1.703	

Omer Ozturk (OSU)

Izmir Economy Univ and TUBITAK

25 /

Two-Sample Problem

- Center $X_{[i]j}$ and $Y_{[i]j}$ by subtracting their median. Let $Z_{[i]j}$, $j = 1, \dots, n_i + m_i$ be the combined centered X- and Y-observations from the *i*-judgment class distributions, $i = 1, \dots, k$.
- We estimate $\xi_{0,1}$ with

$$\hat{\xi}_{0,1}^{N} = \frac{1}{3} - \frac{1}{k} \sum_{i=1}^{k} \left\{ \sum_{j=1}^{N} \hat{F}_{[i]}(z_{(j)}) d\hat{F}(z_{(j)}) \right\}^{2}$$
$$\hat{\xi}_{0,1}^{BW} = \frac{1}{3} - \frac{1}{k} \sum_{i=1}^{k} \left\{ \sum_{s=1}^{k} \hat{\rho}_{s,i} \frac{k+1-i}{k+1} \right\}^{2}$$

- We estimate $\xi_{1,0}$ and σ_{RSS} in a similar fashion.
- We use the test statistics $\hat{T}_{BW} = \frac{\sqrt{N+M}\{\bar{T}-1/2\}}{\hat{\sigma}_{BW}}$, $\hat{T}_N = \frac{\sqrt{N+M}\{\bar{T}-1/2\}}{\hat{\sigma}_N}$ • We expect that \hat{T}_{BW} and \hat{T}_N have an approximate t-distribution Omer Ozturk (OSU) Ranking Error

Estimated Type I error rates. B1- truncated Bown-Wolfe model, B2- Un-truncated BW model, N-nonparametric, P-perfect ranking.

			$\rho =$	0.75		ho = 1.00			
k	n	<i>B</i> 1	B2	Ν	Р	<i>B</i> 1	B2	Ν	Р
2	4	.036	.054	.052	.096	.024	.061	.067	.062
	6	.044	.051	.050	.080.	.031	.057	.053	.051
	10	.047	.049	.054	.079	.034	.047	.062	.047
	12	.045	.047	.052	.081	.042	.054	.049	.055
3	4	.051	.061	.062	.117	.033	.066	.067	.057
	6	.053	.055	.054	.115	.036	.061	.059	.052
	10	.052	.052	.057	.112	.037	.054	.053	.051
	12	.043	.045	.051	.101	.040	.057	.056	.052
5	4	.071	.069	.062	.167	.033	.067	.067	.053
	6	.059	.056	.056	.169	.034	.060	.066	.054
	10	.050	.053	.058	.159	.038	.058	.056	.055
	12	.051	.053	.050	.153	.033	.052	.050	.049

Estimated coverage probabilities. B1- truncated Bown-Wolfe model, B2-Un-truncated BW model, P-perfect ranking.

		ho = 0.75			ŀ	p = 1.00	C
k	n	<i>B</i> 1	B2	Р	<i>B</i> 1	B2	Р
2	4	96.2	94.6	91.7	97.2	93.4	94.7
	6	95.8	95.0	91.5	96.9	94.2	94.4
	10	95.3	95.1	91.7	96.6	95.3	95.0
	12	95.4	95.2	92.2	95.9	94.6	94.6
3	4	95.0	93.9	89.0	96.7	93.5	94.9
	6	94.7	94.5	88.2	96.4	94.1	94.7
	10	94.8	94.8	89.0	96.4	94.6	95.1
	12	95.7	95.4	89.8	96.0	94.3	94.7
5	4	92.9	93.0	82.9	96.9	93.3	94.4
	6	94.7	94.5	88.2	96.6	94.1	94.7
	10	95.0	94.7	84.0	96.2	94.2	94.4
	12	94.9	94.7	84.8	96.6	94.8	95.2

One-Sample Problem

- Let X_{[i]j}, j = 1, · · · , n_i, i = 1, · · · , k be a ranked set sample from distribution F with unique median θ.
- We wish to test $H_0: \theta = 0$ against $H_A: \theta \neq 0$.
- A natural nonparametric test statistic for this test is the sign statistic, S⁺ = ∑_{i=1}^k ∑_{j=1}^{n_i} I(X_{[i]j} > 0).
- Exact null distributing of S^+ involves the convolution of binomial random variables with success probabilities $F_{[i]}(0)$.
- Under perfect ranking F_[i](0), i = 1, ..., k are equal to incomplete beta function and the exact null distribution of S⁺ can be computed.
- Under imperfect ranking, *F*_[i](0), *i* = 1, · · · , *k* need to be estimated with *F*_[i](0), *i* = 1, · · · , *k*.
- With estimated F_[i](0), i = 1, · · · , k, the size of the sing test is stable under imperfect ranking.

Applications

Estimated type I error rate of the sing test

n	Est.	ho = 0.5	ho = 0.75	ho = 1.00			
5	BW1	0.058	0.055	0.042			
	BW2	0.068	0.066	0.057			
	Р	0.082	0.070	0.051			
7	BW1	0.056	0.057	0.045			
	BW2	0.060	0.068	0.058			
	Р	0.079	0.075	0.050			
5	BW1	0.066	0.064	0.040			
	BW2	0.071	0.073	0.060			
	Р	0.112	0.091	0.047			
7	BW1	0.057	0.058	0.045			
	BW2	0.060	0.062	0.063			
	Р	0.102	0.084	0.053			
	5	n Est. 5 BW1 BW2 P 7 BW1 BW2 P 5 BW1 BW2 P 7 BW1 BW2	$\begin{array}{c cccc} n & Est. & \rho = 0.5 \\ \hline 5 & BW1 & 0.058 \\ BW2 & 0.068 \\ P & 0.082 \\ \hline 7 & BW1 & 0.056 \\ BW2 & 0.060 \\ P & 0.079 \\ \hline 5 & BW1 & 0.066 \\ BW2 & 0.071 \\ P & 0.112 \\ \hline 7 & BW1 & 0.057 \\ BW2 & 0.060 \\ \hline \end{array}$	$\begin{array}{c ccccc} n & Est. & \rho = 0.5 & \rho = 0.75 \\ \hline 5 & BW1 & 0.058 & 0.055 \\ BW2 & 0.068 & 0.066 \\ P & 0.082 & 0.070 \\ \hline 7 & BW1 & 0.056 & 0.057 \\ BW2 & 0.060 & 0.068 \\ P & 0.079 & 0.075 \\ \hline 5 & BW1 & 0.066 & 0.064 \\ BW2 & 0.071 & 0.073 \\ P & 0.112 & 0.091 \\ \hline 7 & BW1 & 0.057 & 0.058 \\ BW2 & 0.060 & 0.062 \\ \end{array}$			

30 /

Applications

Estimated coverage probabilities of the median confidence interval

k	n	Est.	$\rho = 0.5$	$\rho = 0.75$	$\rho = 1.00$
2	5	BW1	94.0	94.6	95.9
		BW2	93.3	93.9	94.6
		Р	91.5	92.9	95.2
2	7	BW1	94.4	94.2	95.9
		BW2	94.0	93.3	94.7
		Р	92.1	92.6	95.4
3	5	BW1	93.8	94.1	96.4
		BW2	93.4	93.3	95.0
		Р	88.8	90.9	95.2
3	7	BW1	94.6	94.7	96.2
		BW2	94.5	93.9	94.2
		Р	87.6	91.9	95.2

31 / 34

Example

- An experiment is conducted to test if there is a difference in two spreader settings in in a horticultural experiment.
- The response variable is the percentage area covered by spray deposit on the leaf's upper surface area of apple trees.
- Precise measurement of response is expensive and time consuming with respect to cost of a visual inspection under ultraviolet light.
- Two ranked set samples are collected, one from low spreader settings (A) the other from the high spreader settings (B).
- We wish to test $H_0: \mu_L \mu_H = 0$ against $H_A: \mu_L \mu_H \neq 0$ by using rank-sum statistics.
- The judgment class distributions are estimated under stochastic order restriction.
- The quantity $\xi_{0,1} = \xi_{0,1}$ is estimated $\hat{\xi}_{0,1} = 0.0277$. The test statistic $\hat{T} = 3.635$ and the the P-value is 0.00023. Thus, we reject the null hypothesis.

Omer Ozturk (OSU)

Example

Rank	Low-volume							
Cycle	1	2	3	4	5			
1	0.3	2.8	24.4	5.7	14.3			
2	3.9	11.9	12.6	10.5	56.5			
3	3.4	11.8	13.0	21.8	29.6			
4	5.1	10.4	19.3	21.0	15.0			
5	3.2	14.1	13.0	25.0	22.9			
6	6.9	7.0	26.0	22.5	28.5			
7	10.0	9.1	24.4	13.0	34.7			
8	1.2	9.6	6.9	37.3	13.3			
9	4.6	6.0	12.6	22.3	27.3			
10	2.8	8.3	10.8	21.2	26.1			

Izmir Economy Univ and TUBITAK 33

- We introduced two estimators for the quality of ranking information in a ranked set sample.
- These estimators are used to reduce the effect of imperfect ranking in one and two sample nonparametric statistical procedures.
- These estimated models can easily be extended to other statistical procedures to calibrate the impact of imperfect ranking.